# ON GENERALIZED PSEUDO-PROJECTIVE CURVATURE TENSOR OF PARA-KENMOTSU MANIFOLDS 

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#### Abstract

The object of the present paper is to generalize pseudo-projective curvature tensor of para-Kenmotsu manifold with the help of a new generalized $(0,2)$ symmetric tensor $z$ introduced by Mantica and Suh. Various geometric properties of generalized pseudo-projective curvature tensor of paraKenmotsu manifold have been studied. It is shown that a generalized pseudoprojectively $\phi$-symmetric para-Kenmotsu manifold is an Einstein manifold.


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## 1 Introduction

The projective tensor is one of the major curvature tensors. The study of pseudo-projective curvature tensor has been a very attractive field for investigations in the past decades. A tensor field $\bar{P}$ was defined and studied in 2002 by Bhagwat Prasad [18] on a Riemannian manifold of dimension n, which includes projective curvature tensor $P$. This tensor field $\bar{P}$ referred to as pseudo-projective curvature tensor. In 2011, H.G. Nagaraja and G. Somashekhara [14] extended pseudo-projective curvature tensor in Sasakian manifolds. After 2012, the pseudoprojective curvature tensor analysis in LP-Sasakian manifolds was resumed by

[^0]Y.B. Maralabhavi and G.S. Shivaprasanna [12]. In 2016, S. Mallick, Y.J. Suh and U.C. De [11] defined and studied a space time with pseudo-projective curvature tensor. Subsequently, several researchers performed a study of pseudo-projective curvature tensor in a number of directions, such as $[4,5,13,15,17,21,22]$. The pseudo-projective curvature tensor is defined by [18]
\[

$$
\begin{align*}
\bar{P}(X, Y, U)= & a R(X, Y, U)+b[S(Y, U) X-S(X, U) Y] \\
& -\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) X-g(X, U) Y], \tag{1}
\end{align*}
$$
\]

where a and b are constants such that $\mathrm{a}, \mathrm{b} \neq 0$ and $R$ is the curvature tensor, $S$ is the Ricci tensor and $r$ is the scalar curvature tensor.

The notion of an almost para-contact manifold was introduced by I. Sato [19]. Since the publication of [26], paracontact metric manifolds have been studied by many authors in recent years. The importance of para-Kenmotsu geometry, have been pointed out especially in the last years by several papers highlighting the exchanges with the theory of para-Kähler manifolds and its role in semi-Riemannian geometry and mathematical physics $[3,7,8,20]$.

In this paper, we consider the generalized pseudo-projective curvature tensor of para-Kenmotsu manifolds and study some properties of generalized pseudoprojective curvature tensor. The organisation of the paper is as follows: After preliminaries on para-Kenmotsu manifold in Section 2, we describe briefly the generalized pseudo-projective curvature tensor on para-Kenmotsu manifold in Section 3 and also we study some properties of generalized pseudo-projective curvature tensor in para-Kenmotsu manifold. In Section 4, we study a generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold is an $\eta$ Einstein manifold. Further in the Section 5, we show that a generalized pseudo-projectively Ricci semi-symmetric para-Kenmotsu manifold is either Einstein manifold or $\psi=$ $\frac{a n(n-1)+r a+b r(n-1)}{b n(n-1)}$ on it. In the last section we show that the generalized pseudoprojectively $\phi$-symmetric para-Kenmotsu manifold is an Einstein manifold.

## 2 Preliminaries

An $n$-dimensional differentiable manifold $M^{n}$ is said to have almost paracontact structure $(\phi, \xi, \eta)$, where $\phi$ is a tensor field of type $(1,1), \xi$ is a vector field known as characteristic vector field and $\eta$ is a 1-form satisfying the following relations

$$
\begin{gather*}
\phi^{2}(X)=X-\eta(X) \xi,  \tag{2}\\
\eta(\phi X)=0,  \tag{3}\\
\phi(\xi)=0, \tag{4}
\end{gather*}
$$

and

$$
\begin{equation*}
\eta(\xi)=1 . \tag{5}
\end{equation*}
$$

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A differentiable manifold with almost para-contact structure $(\phi, \xi, \eta)$ is called an almost para-contact manifold. Further, if the manifold $M^{n}$ has a semi-Riemannian metric $g$ satisfying

$$
\begin{equation*}
\eta(X)=g(X, \xi) \tag{6}
\end{equation*}
$$

and

$$
\begin{equation*}
g(\phi X, \phi Y)=-g(X, Y)+\eta(X) \eta(Y) . \tag{7}
\end{equation*}
$$

Then the structure $(\phi, \xi, \eta, g)$ satisfying conditions (2) to (7) is called an almost para-contact Riemannian structure and the manifold $M^{n}$ with such a structure is called an almost para-contact Riemannian manifold [1, 19].

Now we briefly present an account of an analogue of the Kenmotsu manifold in paracontact geometry which will be called para-Kenmotsu.

Definition 1. The almost paracontact metric structure $(\phi, \xi, \eta, g)$ is para-Kenmotsu should this relation hold[2, 16], if the Levi-Civita connection $\nabla$ of $g$ satisfies $\left(\nabla_{X} \phi\right) Y=g(\phi X, Y) \xi-\eta(Y) \phi X$, for any $X, Y \in \mathfrak{X}(M)$.

On a para-Kenmotsu manifold [2, 20], the following relations hold:

$$
\begin{gather*}
\nabla_{X} \xi=X-\eta(X) \xi  \tag{8}\\
\left(\nabla_{X} \eta\right) Y=g(X, Y)-\eta(X) \eta(Y),  \tag{9}\\
\eta(R(X, Y, Z))=g(X, Z) \eta(Y)-g(Y, Z) \eta(X),  \tag{10}\\
R(X, Y, \xi)=\eta(X) Y-\eta(Y) X,  \tag{11}\\
R(X, \xi, Y)=-R(\xi, X, Y)=g(X, Y) \xi-\eta(Y) X,  \tag{12}\\
S(\phi X, \phi Y)=-(n-1) g(\phi X, \phi Y),  \tag{13}\\
S(X, \xi)=-(n-1) \eta(X),  \tag{14}\\
Q \xi=-(n-1) \xi,  \tag{15}\\
r=-n(n-1), \tag{16}
\end{gather*}
$$

for any vector fields $X, Y, Z$, where $Q$ is the Ricci operator that is $g(Q X, Y)=$ $S(X, Y), S$ is the Ricci tensor and $r$ is the scalar curvature.

In A. M. Blaga [2], gave an example on para-Kenmotsu manifold:
Example 1. We consider the three dimensional manifold $M^{3}=\{(x, y, z) \in$ $\left.\mathbb{R}^{3}, z \neq 0\right\}$, where $(x, y, z)$ are the standard co-ordinates in $\mathbb{R}^{3}$. The vector fields

$$
e_{1}:=\frac{\partial}{\partial x}, e_{2}:=\frac{\partial}{\partial y}, e_{3}:=-\frac{\partial}{\partial z}
$$

are linearly independent at each point of the manifold.
Define

$$
\phi:=\frac{\partial}{\partial y} \otimes d x+\frac{\partial}{\partial x} \otimes d y, \xi:=-\frac{\partial}{\partial z}, \eta:=-d z
$$

$$
g:=d x \otimes d x-d y \otimes d y+d z \otimes d z .
$$

Then it follows that

$$
\begin{gathered}
\phi e_{1}=e_{2}, \phi e_{2}=e_{1}, \phi e_{3}=0 \\
\eta\left(e_{1}\right)=0, \eta\left(e_{2}\right)=0, \eta\left(e_{3}\right)=1
\end{gathered}
$$

Let $\nabla$ be the Levi-Civita connetion with respect to metric $g$. Then, we have

$$
\left[e_{1}, e_{2}\right]=0,\left[e_{2}, e_{3}\right]=0,\left[e_{3}, e_{1}\right]=0
$$

The Riemannian connection $\nabla$ of the metric $g$ is deduced from Koszul's formula

$$
\begin{aligned}
2 g\left(\nabla_{X} Y, Z\right) & =X(g(Y, Z))+Y(g(Z, X))-Z(g(X, Y)) \\
& -g(X,[Y, Z])+g(Y,[Z, X])+g(Z,[X, Y]) .
\end{aligned}
$$

Then Koszul's formula yields

$$
\begin{gathered}
\nabla_{e_{1}} e_{1}=-e_{3}, \nabla_{e_{1}} e_{2}=0, \nabla_{e_{1}} e_{3}=e_{1}, \\
\nabla_{e_{2}} e_{1}=0, \nabla_{e_{2}} e_{2}=e_{3}, \nabla_{e_{2}} e_{3}=e_{2}, \\
\nabla_{e_{3}} e_{1}=e_{1}, \nabla_{e_{3}} e_{2}=e_{2}, \nabla_{e_{3}} e_{3}=0 .
\end{gathered}
$$

These results shows that the manifold satisfies

$$
\nabla_{X} \xi=X-\eta(X) \xi
$$

for $\xi=e_{3}$. Hence the manifold under consideration is para-Kenmotsu manifold of dimension three.

A para-Kenmotsu manifold is said to be an $\eta$-Einstein manifold if its Ricci tensor $S$ is of the form

$$
\begin{equation*}
S(X, Y)=a g(X, Y)+b \eta(X) \eta(Y) \tag{17}
\end{equation*}
$$

for the vector fields $X, Y$, where a and b are functions on $M^{n}$.

## 3 Generalized pseudo-projective curvature tensor of para-Kenmotsu manifold

In this section, we give a brief account of generalized pseudo-projective curvature tensor of para-Kenmotsu manifold and study various geometric properties of it.

The pseudo-projective curvature tensor of para-Kenmotsu manifold $M^{n}$ is given by the following relation:

$$
\begin{align*}
\bar{P}(X, Y, U)= & a R(X, Y, U)+b[S(Y, U) X-S(X, U) Y] \\
& -\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) X-g(X, U) Y], \tag{18}
\end{align*}
$$

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Also, the type $(0,4)$ tensor field ${ }^{\prime} \bar{P}$ is given by

$$
\begin{array}{r}
\bar{P}(X, Y, U, V)=a^{\prime} R(X, Y, U, V)+b[S(Y, U) g(X, V)-S(X, U) \\
g(Y, V)]-\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) g(X, V)-g(X, U) g(Y, V)] \tag{19}
\end{array}
$$

where

$$
' \bar{P}(X, Y, U, V)=g(\bar{P}(X, Y, U), V)
$$

and

$$
{ }^{\prime} R(X, Y, U, V)=g(R(X, Y, U), V)
$$

for the arbitrary vector fields $X, Y, U, V$.
Differentiating covariantly with respect to $W$ in equation (18), we get

$$
\begin{array}{r}
\left.\left.\left(\nabla_{W} \bar{P}\right)(X, Y) U\right)=a\left(\nabla_{W} R\right)(X, Y) U\right)+b\left[\left(\nabla_{W} S\right)(Y, U) X\right. \\
\left.-\left(\nabla_{W} S\right)(X, U) Y\right]-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) X-g(X, U) Y] . \tag{20}
\end{array}
$$

Divergence of pseudo-projective curvature tensor in equation (18) is given by

$$
\begin{array}{r}
(\operatorname{div} \bar{P})(X, Y) U)=a(\operatorname{div} R)(X, Y) U)+b\left[\left(\nabla_{X} S\right)(Y, U)\right. \\
\left.-\left(\nabla_{Y} S\right)(X, U)\right]-(\operatorname{divr})\left[\frac{a+b(n-1)}{n(n-1)}\right][g(Y, U) \operatorname{div}(X)  \tag{21}\\
-g(X, U) \operatorname{div}(Y)] .
\end{array}
$$

But

$$
\begin{equation*}
(\operatorname{div} R)(X, Y) U)=\left(\nabla_{X} S\right)(Y, U)-\left(\nabla_{Y} S\right)(X, U) \tag{22}
\end{equation*}
$$

From equations (21) and (22), we have

$$
\begin{align*}
&(\operatorname{div} \bar{P})(X, Y) U=(a+b)\left[\left(\nabla_{X} S\right)(Y, U)-\left(\nabla_{Y} S\right)(X, U)\right]-(\operatorname{divr}) \\
& {\left[\frac{a+b(n-1)}{n(n-1)}\right][g(Y, U) \operatorname{div}(X)-g(X, U) \operatorname{div}(Y)] . } \tag{23}
\end{align*}
$$

Definition 2. An almost paracontact structure $(\phi, \xi, \eta, g)$ is said to be locally pseudo-projectively symmetric if

$$
\begin{equation*}
\left(\nabla_{W} \bar{P}\right)(X, Y, U)=0 \tag{24}
\end{equation*}
$$

for all vector fields $X, Y, U, W \in T_{p} M^{n}$.
Definition 3. An almost paracontact structure $(\phi, \xi, \eta, g)$ is said to be locally pseudo-projectively $\phi$-symmetric if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} \bar{P}\right)(X, Y, U)\right)=0 \tag{25}
\end{equation*}
$$

for all vector fields $X, Y, U, W$ orthogonal to $\xi$.

Definition 4. An almost paracontact structure $(\phi, \xi, \eta, g)$ is said to be pseudoprojectively $\phi$-recurrent if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} \bar{P}\right)(X, Y, U)\right)=A(W) \bar{P}(X, Y, U) \tag{26}
\end{equation*}
$$

for arbitrary vector fields $X, Y, U, W$.
If the 1 -form $A$ vanishes, then the manifold reduces to a locally pseudoprojectively $\phi$-symmetric.

A new generalized $(0,2)$ symmetric tensor 2 , defined by Mantica and Suh [9], is given by the following relation

$$
\begin{equation*}
z(X, Y)=S(X, Y)+\psi g(X, Y) \tag{27}
\end{equation*}
$$

where $\psi$ is an arbitrary scalar function.
From equation (27), we have

$$
\begin{equation*}
z(\phi X, \phi Y)=S(\phi X, \phi Y)+\psi g(\phi X, \phi Y), \tag{28}
\end{equation*}
$$

which, on using equations (7) and (13), gives

$$
\begin{equation*}
z(\phi X, \phi Y)=[\psi-(n-1)][-g(X, Y)+\eta(X) \eta(Y)] . \tag{29}
\end{equation*}
$$

From equation (19), we have

$$
\begin{gather*}
\bar{P}(X, Y, U, V)=a^{\prime} R(X, Y, U, V)+b[S(Y, U) g(X, V)-S(X, U) \\
g(Y, V)]-\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) g(X, V)-g(X, U) g(Y, V)] . \tag{30}
\end{gather*}
$$

From equation (27) the above equation reduces to

$$
\begin{array}{r}
\bar{P}(X, Y, U, V)=a^{\prime} R(X, Y, U, V)+b[z(Y, U) g(X, V)-z(X, U) \\
g(Y, V)]-\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) g(X, V)-g(X, U) g(Y, V)]  \tag{31}\\
+b \psi[g(Y, V) g(X, U)-g(Y, U) g(X, V)]
\end{array}
$$

If we put

$$
\begin{array}{r}
\overline{\bar{P}}(X, Y, U, V)=a^{\prime} R(X, Y, U, V)+b[z(Y, U) g(X, V)-z(X, U) \\
\quad g(Y, V)]-\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) g(X, V)-g(X, U) g(Y, V)] \tag{32}
\end{array}
$$

Then equation (31) reduces to

$$
\begin{align*}
\prime \overline{\bar{P}}(X, Y, U, V)=^{\prime} \bar{P}(X, Y, U, V)- & b \psi \tag{33}
\end{align*} \quad[g(Y, V) g(X, U), ~-g(X, V) g(Y, U)] .
$$

We call this new tensor ${ }^{\prime} \overline{\bar{P}}$ given in equation (32) as generalized pseudo-projective curvature tensor of para-Kenmotsu manifold.

If $\psi=0$, then from eqauation (33), we have

$$
\begin{equation*}
' \overline{\bar{P}}(X, Y, U, V)=^{\prime} \bar{P}(X, Y, U, V) \tag{34}
\end{equation*}
$$

If the scalar function $\psi$ vanishes on para-Kenmotsu manifold, then the pseudoprojective curvature tensor and generalized pseudo-projective curvature tensor are identicle.

Theorem 1. Generalized pseudo-projective curvature tensor $\overline{\bar{P}}$ of para-Kenmotsu manifold is
(a) skew symmetric in first two slots.
(b) skew symmetric in last two slots.
(c) symmetric in pair of slots.

Proof. (a) From equation (33), we have

$$
\begin{align*}
\overline{\bar{P}}_{\bar{P}}(Y, X, U, V)=^{\prime} \bar{P}(Y, X, U, V)- & b \psi  \tag{35}\\
& -g(Y(X, V) g(Y, U) g(X, U)] .
\end{align*}
$$

Now adding equations (33) and (35) and using the following

$$
' \bar{P}(X, Y, U, V)+{ }^{\prime} \bar{P}(Y, X, U, V)=0
$$

we get

$$
\prime \overline{\bar{P}}(X, Y, U, V)=-^{\prime} \overline{\bar{P}}(Y, X, U, V)
$$

which shows that generalized pseudo-projective curvature tensor $/ \overline{\bar{P}}$ is skew symmetric in first two slots.
(b) Again from equation (33), we have

$$
\begin{align*}
\prime \overline{\bar{P}}(X, Y, V, U)=^{\prime} \bar{P}(X, Y, V, U)- & b \psi[g(X, V) g(Y, U)  \tag{36}\\
& -g(Y, V) g(X, U)] .
\end{align*}
$$

Now, adding (33) and (36) and using the following

$$
' \bar{P}(X, Y, U, V)+{ }^{\prime} \bar{P}(X, Y, V, U)=0
$$

we obtain

$$
\prime \overline{\bar{P}}(X, Y, U, V)=-\overline{\bar{P}}(X, Y, V, U)
$$

which shows that generalized pseudo-projective curvature tensor ${ }^{\prime} \overline{\bar{P}}$ is skew symmetric in last two slots.
(c) From equation (33), interchanging pair of slots $X$ by $U$ and $Y$ by $V$, we have

$$
\begin{align*}
& \prime \overline{\bar{P}}(U, V, X, Y)=^{\prime} \bar{P}(U, V, X, Y)-b \psi[g(V, Y) g(U, X)  \tag{37}\\
&-g(U, Y) g(V, X)] .
\end{align*}
$$

Now, using equations (33) and (37) and using the following

$$
' \bar{P}(X, Y, U, V)=^{\prime} \bar{P}(U, V, X, Y)
$$

we get

$$
' \overline{\bar{P}}(X, Y, U, V)=^{\prime} \overline{\bar{P}}(U, V, X, Y)
$$

which shows that generalized pseudo-projective curvature tensor ${ }^{\prime} \overline{\bar{P}}$ is symmetric in pair of slots.

Theorem 2. Generalized pseudo-projective curvature tensor of para-Kenmotsu manifold satisfies Bianchi's first identity.

Proof. From equation (33), we have

$$
\begin{equation*}
\overline{\bar{P}}(X, Y, U)=\bar{P}(X, Y, U)-b \psi[g(X, U) Y-g(Y, U) X)] \tag{38}
\end{equation*}
$$

Writing two more equations by the cyclic permutations of $X, Y$ and $U$ in the above equation, we get

$$
\begin{equation*}
\overline{\bar{P}}(Y, U, X)=\bar{P}(Y, U, X)-b \psi[g(Y, X) U-g(U, X) Y)] \tag{39}
\end{equation*}
$$

and

$$
\begin{equation*}
\overline{\bar{P}}(U, X, Y)=\bar{P}(U, X, Y)-b \psi[g(U, Y) X-g(X, Y) U)] . \tag{40}
\end{equation*}
$$

Adding equations (38), (39) and (40) with the fact that

$$
\bar{P}(X, Y, U)+\bar{P}(Y, U, X)+\bar{P}(U, X, Y)=0
$$

we get

$$
\overline{\bar{P}}(X, Y, U)+\overline{\bar{P}}(Y, U, X)+\overline{\bar{P}}(U, X, Y)=0
$$

which shows that generalized pseudo-projective curvature tensor of para-Kenmotsu manifold satisfies Bianchi's first identity.

Theorem 3. Generalized pseudo-projective curvature tensor of para-Kenmotsu manifold satisfies the following identites:

$$
\begin{array}{r}
(a) \overline{\bar{P}}(\xi, Y, U)=-\overline{\bar{P}}(Y, \xi, U)=g(Y, U)\left[-a-\frac{r}{n}\left(\frac{a}{n-1}+b\right)+b \psi\right] \\
\xi+\left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right] \eta(U) Y \\
+b S(Y, U) \xi, \\
(b) \overline{\bar{P}}(X, Y, \xi)=\left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right][\eta(X) Y \\
-\eta(Y) X] \\
(c) \eta(\overline{\bar{P}}(U, V, Y))=\left[a+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right][g(U, Y) \eta(V)  \tag{43}\\
-g(V, Y) \eta(U)]+b[S(V, Y) \eta(U)-S(U, Y) \eta(V)]
\end{array}
$$

Proof. (a) Putting $X=\xi$ in equation (38), we have

$$
\overline{\bar{P}}(\xi, Y, U)=\bar{P}(\xi, Y, U)-b \psi[g(\xi, U) Y-g(Y, U) \xi],
$$

which on using equations $(6),(12),(14),(18)$, gives the desired result.
(b) Again putting $U=\xi$ in equation (38), we have

$$
\overline{\bar{P}}(X, Y, \xi)=\bar{P}(X, Y, \xi)-b \psi[g(X, \xi) Y-g(Y, \xi) X] .
$$

With the use of equations (6), (11), (14), (18) in the above equation, we obtain the required result.
(c) Taking innner product with $\xi$ of equation (38), we have

$$
\eta(\overline{\bar{P}}(U, V, Y))=\eta(\bar{P}(U, V, Y))-b \psi[g(U, Y) \eta(V)-g(V, Y) \eta(U)],
$$

which on using equations (6), (10), (18), gives the desired result.

## 4 Generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold

Definition 5. A Para-Kenmotsu manifold is said to be semi-symmetric [23] if it satisfies the condition

$$
\begin{equation*}
R(X, Y) \cdot R=0 \tag{44}
\end{equation*}
$$

where $R(X, Y)$ is considered as the derivation of the tensor algebra at each point of the manifold.

Definition 6. A para-Kenmotsu manifold is said to be generalized pseudoprojectively semi-symmetric if it satisfies the condition

$$
\begin{equation*}
R(X, Y) \cdot \overline{\bar{P}}=0 \tag{45}
\end{equation*}
$$

where $\overline{\bar{P}}$ is generalized pseudo-projective curvature tensor and $R(X, Y)$ is considered as the derivation of the tensor algebra at each point of the manifold.

Theorem 4. A generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold is an $\eta$-Einstein manifold.

Proof. Consider

$$
(R(\xi, X) \cdot \overline{\bar{P}})(U, V, Y)=0
$$

for any $X, Y, U, V \in T_{P} M$, where $\overline{\bar{P}}$ is generalized Pseudo-projective curvature tensor.
Then we have

$$
\begin{array}{r}
R(\xi, X, \overline{\bar{P}}(U, V, Y))-\overline{\bar{P}}(R(\xi, X, U), V, Y)  \tag{46}\\
-\overline{\bar{P}}(U, R(\xi, X, V), Y)-\overline{\bar{P}}(U, V, R(\xi, X, Y)=0
\end{array}
$$

In view of equation (12) the above equation takes the form

$$
\begin{array}{r}
\eta(\overline{\bar{P}}(U, V, Y)) X-^{\prime} \overline{\bar{P}}(U, V, Y, X) \xi-\eta(U) \overline{\bar{P}}(X, V, Y)+g(X, U) \\
\overline{\bar{P}}(\xi, V, Y)-\eta(V) \overline{\bar{P}}(U, X, Y)+g(X, V) \overline{\bar{P}}(U, \xi, Y)-\eta(Y) \overline{\bar{P}}(U, V, X) \\
+g(X, Y) \overline{\bar{P}}(U, V, \xi)=0 .
\end{array}
$$

Taking inner product of above eqquation with $\xi$ and using equations (5), (33), (41), (42), (43), we get

$$
\begin{array}{r}
-\bar{P}(U, V, Y, X)+b \psi[g(X, V) g(Y, U)-g(X, U) g(Y, V)]-b g(X, V) \\
S(Y, U)-\left[a+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right][g(X, U) \eta(Y) \eta(V)-g(X, V) \\
\eta(Y) \eta(U)]-\left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right] g(X, V) \eta(Y) \eta(U) \\
+b g(X, U) S(Y, V)-b[S(X, V) \eta(U) \eta(Y)-S(X, U) \eta(V) \eta(Y)] \\
+g(X, U) \eta(Y) \eta(V)\left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right] \\
-g(X, V) g(Y, U)\left[-a-\frac{r}{n}\left(\frac{a}{n-1}+b\right)+b \psi\right]+g(X, U) g(Y, V) \\
{\left[-a-\frac{r}{n}\left(\frac{a}{n-1}+b\right)+b \psi\right]=0 .}
\end{array}
$$

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By virtue of equation (19), the above equation reduces to

$$
\begin{array}{r}
-a^{\prime} R(U, V, Y, X)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)[g(Y, V) g(U, X)-g(Y, U) \\
g(V, X)]-\left[a+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right][g(U, X) \eta(Y) \eta(V) \\
-g(V, X) \eta(Y) \eta(U)]+\left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right] \\
g(X, U) \eta(Y) \eta(V)-\left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right] \\
g(X, V) \eta(Y) \eta(U)-g(X, V) g(Y, U)\left[-a-\frac{r}{n}\left(\frac{a}{n-1}+b\right)+b \psi\right] \\
+g(X, U) g(Y, V)\left[-a-\frac{r}{n}\left(\frac{a}{n-1}+b\right)+b \psi\right] \\
-b[S(X, V) \eta(U) \eta(Y)-S(X, U) \eta(V) \eta(Y)] \\
+b \psi[g(Y, U) g(X, V)-g(Y, V) g(X, U)]=0 .
\end{array}
$$

Let $\left\{e_{i}: i=1,2 \ldots . . n\right\}$ be an orthonormal basis. Putting $X=U=e_{i}$ in the above equation and taking summation over $i$, we get

$$
S(Y, V)=-(n-1) g(Y, V)+\frac{2 n b}{a} \eta(Y) \eta(V)
$$

This shows that generalized pseudo-projectively semi-symmetric paraKenmotsu manifold is an $\eta$-Einstein manifold.

## 5 Generalized pseudo-projectively Ricci semisymmetric para-Kenmotsu manifold

Definition 7. Para-Kenmotsu manifold $M$ is said to be Ricci semi-symmetric [10] if the condition

$$
\begin{equation*}
R(X, Y) \cdot S=0 \tag{47}
\end{equation*}
$$

holds for all $X, Y \in T_{p} M$.

Definition 8. Para-Kenmotsu manifold is said to be generalized pseudo-projectively Ricci semi-symmetric if the condition

$$
\begin{equation*}
\overline{\bar{P}}(X, Y) \cdot S=0 \tag{48}
\end{equation*}
$$

holds for all $X, Y$, where $\overline{\bar{P}}$ is generalized pseudo-projective curvature tensor of para-Kenmotsu manifold.

Theorem 5. A generalized pseudo-projectively Ricci semi-symmetric para-Kenmotsu manifold is either Einstein manifold or $\psi=\frac{a n(n-1)+r a+b r(n-1)}{b n(n-1)}$ on it.

Proof. Consider

$$
(\overline{\bar{P}}(\xi, X) \cdot S)(U, V)=0
$$

which gives

$$
S(\overline{\bar{P}}(\xi, X, U), V)+S(U, \overline{\bar{P}}(\xi, X, V))=0
$$

Using equations (14) and (41) in the above equation, we get

$$
\begin{aligned}
0 & =\left[a+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right][S(X, V) \eta(U)+S(X, U) \eta(V)] \\
& -(n-1)\left[-a-\frac{r}{n}\left(\frac{a}{n-1}+b\right)+b \psi\right][g(X, U) \eta(V)+g(X, V) \eta(U)]
\end{aligned}
$$

Putting $U=\xi$ in the above equation and using (5), (6) and (14), we get

$$
\left[a+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b \psi\right][S(X, V)+(n-1) g(X, V)]=0,
$$

which gives either

$$
\psi=\frac{a n(n-1)+r a+b r(n-1)}{b n(n-1)}
$$

or

$$
S(X, V)=-(n-1) g(X, V)
$$

This shows that generalized pseudo-projectively Ricci semi-symmetric para-Kenmotsu manifold is an Einstein manifold.

## 6 Generalized pseudo-projectively $\phi$-symmetric paraKenmotsu manifold

Definition 9. A para-Kenmotsu manifold $M^{n}$ is said to be locally $\phi$-symmetric if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} R\right)(X, Y, U)\right)=0 \tag{49}
\end{equation*}
$$

for all vector fields $X, Y, U, W$ orthogonal to $\xi$.
This notion was introduced by Takahashi for Sasakian manifolds [24].
Definition 10. A para-Kenmotsu manifold is said to be $\phi$-symmetric if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} R\right)(X, Y, U)\right)=0, \tag{50}
\end{equation*}
$$

for arbitrary vector fields $X, Y, U, W$.
This notion was also introduced by Takahashi for Sasakian manifold [25]. Also analogous to these definitons, we define

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Definition 11. A para-Kenmotsu manifold $M^{n}$ is said to be generalized pseudoprojective locally $\phi$-symmetric para-Kenmotsu manifold if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)\right)=0 \tag{51}
\end{equation*}
$$

for all vector fields $X, Y, U, W$ orthogonal to $\xi$.
And also
Definition 12. A para-Kenmotsu manifold $M^{n}$ is said to be generalized pseudoprojectively $\phi$-symmetric para-Kenmotsu manifold if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)\right)=0 \tag{52}
\end{equation*}
$$

for arbitary vector fields $X, Y, U, W$.
Theorem 6. A generalized pseudo projectively $\phi$-symmetric para Kenmotsu manifold is an Einstein manifold.

Proof. Taking covariant derivative of equation (38) with respect to vector field $W$, we obtain

$$
\begin{equation*}
\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)=\left(\nabla_{W} \bar{P}\right)(X, Y, U)-b d r(\psi)[g(X, U) Y-g(Y, U) X] . \tag{53}
\end{equation*}
$$

Using equation (20) in the above equation, we get

$$
\begin{array}{r}
\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)=a\left(\nabla_{W} R\right)(X, Y, U)-b d r(\psi)[g(X, U) Y \\
-g(Y, U) X]+b\left[\left(\nabla_{W} S\right)(Y, U) X-\left(\nabla_{W} S\right)(X, U) Y\right]-\frac{d r(W)}{n}  \tag{54}\\
\left(\frac{a}{n-1}+b\right)[g(Y, U) X-g(X, U) Y]
\end{array}
$$

Assume that the manifold is generalized pseudo-projectively $\phi$-symmetric, then from equation (52), we have

$$
\phi^{2}\left(\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)\right)=0
$$

which on using equation (2), gives

$$
\begin{equation*}
\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)=\eta\left(\left(\nabla_{W} \overline{\bar{P}}\right)(X, Y, U)\right) \xi \tag{55}
\end{equation*}
$$

Using equation (54) in above equation, we get

$$
\begin{array}{r}
a\left(\nabla_{W} R\right)(X, Y, U)-b d r(\psi)[g(X, U) Y-g(Y, U) X]+b \\
{\left[\left(\nabla_{W} S\right)(Y, U) X-\left(\nabla_{W} S\right)(X, U) Y\right]-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right)} \\
{[g(Y, U) X-g(X, U) Y]=a \eta\left(\left(\nabla_{W} R\right)(X, Y, U)\right) \xi-b d r(\psi)}  \tag{56}\\
{[g(X, U) \eta(Y)-g(Y, U) \eta(X)] \xi+b\left[\left(\nabla_{W} S\right)(Y, U) \eta(X)\right.} \\
\left.-\left(\nabla_{W} S\right)(X, U) \eta(Y)\right] \xi-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right) \\
{[g(Y, U) \eta(X)-g(X, U) \eta(Y)] \xi,}
\end{array}
$$

Taking inner product of the above equation with $V$, we get

$$
\begin{array}{r}
a g\left(\left(\nabla_{W} R\right)(X, Y, U), V\right)-b d r(\psi)[g(X, U) g(Y, V)-g(Y, U) \\
g(X, V)]+b\left[\left(\nabla_{W} S\right)(Y, U) g(X, V)-\left(\nabla_{W} S\right)(X, U) g(Y, V)\right] \\
-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right)[g(Y, U) g(X, V)-g(X, U) g(Y, V)] \\
=a \eta\left(\left(\nabla_{W} R\right)(X, Y, U)\right) \eta(V)-b d r(\psi)[g(X, U) \eta(Y) \eta(V)  \tag{57}\\
-g(Y, U) \eta(X) \eta(V)]+b\left[\left(\nabla_{W} S\right)(Y, U) \eta(X) \eta(V)\right. \\
\left.-\left(\nabla_{W} S\right)(X, U) \eta(Y) \eta(V)\right]-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right) \\
{[g(Y, U) \eta(X) \eta(V)-g(X, U) \eta(Y) \eta(V)] .}
\end{array}
$$

Putting $X=V=e_{i}$ and taking summation over $i$, we obtaion

$$
\begin{array}{r}
a\left(\nabla_{W} S\right)(Y, U)+b\left[n\left(\nabla_{W} S\right)(Y, U)-\left(\nabla_{W} S\right)(Y, U)\right] \\
-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right)[n g(Y, U)-g(Y, U)] \\
-b d r(\psi)[g(Y, U)-n g(Y, U)]-a \eta\left(\left(\nabla_{W} R\right)\left(e_{i}, Y, U\right)\right) \eta\left(e_{i}\right)  \tag{58}\\
-b\left[\left(\nabla_{W} S\right)(Y, U)-\left(\nabla_{W} S\right)\left(e_{i}, U\right) \eta(Y) \eta\left(e_{i}\right)+\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right)\right. \\
{[g(Y, U)-\eta(Y) \eta(U)]+b d r(\psi)[\eta(U) \eta(Y)-g(Y, U)]=0,}
\end{array}
$$

Taking $U=\xi$ in the above equation, we have

$$
\begin{array}{r}
a\left(\nabla_{W} S\right)(Y, \xi)+b(n-1)\left(\nabla_{W} S\right)(Y, \xi)-\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right) \\
(n-1) \eta(Y)-a \eta\left(\left(\nabla_{W} R\right)\left(e_{i}, Y, \xi\right)\right) \eta\left(e_{i}\right)+b d r(\psi)(n-1) \eta(Y)  \tag{59}\\
-b\left[\left(\nabla_{W} S\right)(Y, \xi)-\left(\nabla_{W} S\right)\left(e_{i}, \xi\right) \eta\left(e_{i}\right) \eta(Y)\right]=0 .
\end{array}
$$

Now

$$
\begin{equation*}
\eta\left(\left(\nabla_{W} R\right)\left(e_{i}, Y, \xi\right) \eta\left(e_{i}\right)=g\left(\left(\nabla_{W} R\right)\left(e_{i}, Y, \xi\right), \xi\right) g\left(e_{i}, \xi\right)\right. \tag{60}
\end{equation*}
$$

Also

$$
\begin{align*}
g\left(\left(\nabla_{W} R\right)\left(e_{i}, Y, \xi\right), \xi\right) & =g\left(\nabla_{W} R\left(e_{i}, Y, \xi\right), \xi\right)-g\left(R\left(\nabla_{W} e_{i}, Y, \xi\right), \xi\right) \\
& -g\left(R\left(e_{i}, \nabla_{W} Y, \xi\right), \xi\right)-g\left(R\left(e_{i}, Y, \nabla_{W} \xi\right), \xi\right) . \tag{61}
\end{align*}
$$

Since $\left\{e_{i}\right\}$ is an orthonormal basis, so $\nabla_{X} e_{i}=0$ and using equation (11), we get

$$
g\left(R\left(e_{i}, \nabla_{W} Y, \xi\right), \xi\right)=0
$$

Since

$$
g\left(R\left(e_{i}, Y, \xi\right), \xi\right)+g\left(R(\xi, \xi, Y), e_{i}\right)=0
$$

Therefore, we have

$$
g\left(\nabla_{W} R\left(e_{i}, Y, \xi\right), \xi\right)+g\left(R\left(e_{i}, Y, \xi\right), \nabla_{W} \xi\right)=0
$$

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Using this fact in equation (61), we get

$$
\begin{equation*}
g\left(\left(\nabla_{W} R\right)\left(e_{i}, Y, \xi\right), \xi\right)=0 \tag{62}
\end{equation*}
$$

Using equation (62) in (59), we have

$$
\begin{array}{r}
{\left[\frac{d r(W)}{n}\left(\frac{a}{n-1}+b\right)(n-1) \eta(Y)-b d r(\psi)(n-1) \eta(Y)\right]} \\
{\left[\frac{1}{a+b(n-1)-b}\right]=\left(\nabla_{W} S\right)(Y, \xi),} \tag{63}
\end{array}
$$

Taking $Y=\xi$ in above equation and using equations (5) and (14), we get

$$
\begin{equation*}
d r(\psi)=\frac{d r(W)}{b n}\left(\frac{a}{n-1}+b\right), \tag{64}
\end{equation*}
$$

which shows that $r$ is constant. Now we have

$$
\left(\nabla_{W} S\right)(Y, \xi)=\nabla_{W} S(Y, \xi)-S\left(\nabla_{W} Y, \xi\right)-S\left(Y, \nabla_{W} \xi\right)
$$

Then by using (8), (9), (14) in the above equation, it follows that

$$
\begin{equation*}
\left(\nabla_{W} S\right)(Y, \xi)=-S(Y, W)-(n-1) g(Y, W) \tag{65}
\end{equation*}
$$

Thus from equations (63), (64) and (65), we obtain

$$
\begin{equation*}
S(Y, W)=-(n-1) g(Y, W), \tag{66}
\end{equation*}
$$

which shows that $M^{n}$ is an Einstein manifold.

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