Bulletin of the *Transilvania* University of Braşov Series III: Mathematics and Computer Science, Vol. 1(63), No. 1 - 2021, 143-160 https://doi.org/10.31926/but.mif.2021.1.63.1.11

ON GENERALIZED PSEUDO-PROJECTIVE CURVATURE TENSOR OF PARA-KENMOTSU MANIFOLDS

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Abstract

The object of the present paper is to generalize pseudo-projective curvature tensor of para-Kenmotsu manifold with the help of a new generalized (0,2) symmetric tensor \mathcal{Z} introduced by Mantica and Suh. Various geometric properties of generalized pseudo-projective curvature tensor of para-Kenmotsu manifold have been studied. It is shown that a generalized pseudoprojectively ϕ -symmetric para-Kenmotsu manifold is an Einstein manifold.

2010 Mathematics Subject Classification: 53C15, 53C25.

Key words: Pseudo-projective curvature tensor, para-Kenmotsu manifold, Einstein manifold, η -Einstein manifold, Generalized pseudo-projective curvature tensor.

1 Introduction

The projective tensor is one of the major curvature tensors. The study of pseudo-projective curvature tensor has been a very attractive field for investigations in the past decades. A tensor field \overline{P} was defined and studied in 2002 by Bhagwat Prasad [18] on a Riemannian manifold of dimension n, which includes projective curvature tensor P. This tensor field \overline{P} referred to as pseudo-projective curvature tensor. In 2011, H.G. Nagaraja and G. Somashekhara [14] extended pseudo-projective curvature tensor in Sasakian manifolds. After 2012, the pseudo-projective curvature tensor analysis in LP-Sasakian manifolds was resumed by

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Y.B. Maralabhavi and G.S. Shivaprasanna [12]. In 2016, S. Mallick, Y.J. Suh and U.C. De [11] defined and studied a space time with pseudo-projective curvature tensor. Subsequently, several researchers performed a study of pseudo-projective curvature tensor in a number of directions, such as [4, 5, 13, 15, 17, 21, 22]. The pseudo-projective curvature tensor is defined by [18]

$$\overline{P}(X,Y,U) = aR(X,Y,U) + b[S(Y,U)X - S(X,U)Y] - \frac{r}{n}\left(\frac{a}{n-1} + b\right)[g(Y,U)X - g(X,U)Y],$$
(1)

where a and b are constants such that a, $b \neq 0$ and R is the curvature tensor, S is the Ricci tensor and r is the scalar curvature tensor.

The notion of an almost para-contact manifold was introduced by I. Sato [19]. Since the publication of [26], paracontact metric manifolds have been studied by many authors in recent years. The importance of para-Kenmotsu geometry, have been pointed out especially in the last years by several papers highlighting the exchanges with the theory of para-Kähler manifolds and its role in semi-Riemannian geometry and mathematical physics [3, 7, 8, 20].

In this paper, we consider the generalized pseudo-projective curvature tensor of para-Kenmotsu manifolds and study some properties of generalized pseudoprojective curvature tensor. The organisation of the paper is as follows: After preliminaries on para-Kenmotsu manifold in Section 2, we describe briefly the generalized pseudo-projective curvature tensor on para-Kenmotsu manifold in Section 3 and also we study some properties of generalized pseudo-projective curvature tensor in para-Kenmotsu manifold. In Section 4, we study a generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold is an η Einstein manifold. Further in the Section 5, we show that a generalized pseudo-projectively Ricci semi-symmetric para-Kenmotsu manifold is either Einstein manifold or $\psi = \frac{an(n-1)+ra+br(n-1)}{bn(n-1)}$ on it. In the last section we show that the generalized pseudoprojectively ϕ -symmetric para-Kenmotsu manifold is an Einstein manifold.

2 Preliminaries

An *n*-dimensional differentiable manifold M^n is said to have almost paracontact structure (ϕ, ξ, η) , where ϕ is a tensor field of type (1, 1), ξ is a vector field known as characteristic vector field and η is a 1-form satisfying the following relations

$$\phi^2(X) = X - \eta(X)\xi,\tag{2}$$

$$\eta(\phi X) = 0, \tag{3}$$

$$\phi(\xi) = 0,\tag{4}$$

and

$$\eta(\xi) = 1. \tag{5}$$

A differentiable manifold with almost para-contact structure (ϕ, ξ, η) is called an almost para-contact manifold. Further, if the manifold M^n has a semi-Riemannian metric g satisfying

$$\eta(X) = g(X,\xi) \tag{6}$$

and

$$g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y).$$
(7)

Then the structure (ϕ, ξ, η, g) satisfying conditions (2) to (7) is called an almost para-contact Riemannian structure and the manifold M^n with such a structure is called an almost para-contact Riemannian manifold [1, 19].

Now we briefly present an account of an analogue of the Kenmotsu manifold in paracontact geometry which will be called para-Kenmotsu.

Definition 1. The almost paracontact metric structure (ϕ, ξ, η, g) is para-Kenmotsu should this relation hold[2, 16], if the Levi-Civita connection ∇ of g satisfies $(\nabla_X \phi)Y = g(\phi X, Y)\xi - \eta(Y)\phi X$, for any $X, Y \in \mathfrak{X}(M)$.

On a para-Kenmotsu manifold [2, 20], the following relations hold:

$$\nabla_X \xi = X - \eta(X)\xi,\tag{8}$$

$$(\nabla_X \eta) Y = g(X, Y) - \eta(X) \eta(Y), \tag{9}$$

$$\eta(R(X,Y,Z)) = g(X,Z)\eta(Y) - g(Y,Z)\eta(X), \tag{10}$$

$$R(X, Y, \xi) = \eta(X)Y - \eta(Y)X, \tag{11}$$

$$R(X,\xi,Y) = -R(\xi,X,Y) = g(X,Y)\xi - \eta(Y)X,$$
(12)

$$S(\phi X, \phi Y) = -(n-1)g(\phi X, \phi Y), \qquad (13)$$

$$S(X,\xi) = -(n-1)\eta(X),$$
 (14)

$$Q\xi = -(n-1)\xi,\tag{15}$$

$$r = -n(n-1),\tag{16}$$

for any vector fields X, Y, Z, where Q is the Ricci operator that is g(QX, Y) = S(X, Y), S is the Ricci tensor and r is the scalar curvature.

In A. M. Blaga [2], gave an example on para-Kenmotsu manifold:

Example 1. We consider the three dimensional manifold $M^3 = \{(x, y, z) \in \mathbb{R}^3, z \neq 0\}$, where (x, y, z) are the standard co-ordinates in \mathbb{R}^3 . The vector fields

$$e_1 := \frac{\partial}{\partial x}, e_2 := \frac{\partial}{\partial y}, e_3 := -\frac{\partial}{\partial z}$$

are linearly independent at each point of the manifold. Define

$$\phi := \frac{\partial}{\partial y} \otimes dx + \frac{\partial}{\partial x} \otimes dy, \xi := -\frac{\partial}{\partial z}, \eta := -dz,$$

$$g := dx \otimes dx - dy \otimes dy + dz \otimes dz.$$

Then it follows that

$$\phi e_1 = e_2, \phi e_2 = e_1, \phi e_3 = 0,$$

$$\eta(e_1) = 0, \eta(e_2) = 0, \eta(e_3) = 1.$$

Let ∇ be the Levi-Civita connetion with respect to metric g. Then, we have

$$[e_1, e_2] = 0, [e_2, e_3] = 0, [e_3, e_1] = 0$$

The Riemannian connection ∇ of the metric g is deduced from Koszul's formula

$$2g(\nabla_X Y, Z) = X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y)) - g(X, [Y, Z]) + g(Y, [Z, X]) + g(Z, [X, Y]).$$

Then Koszul's formula yields

$$\nabla_{e_1}e_1 = -e_3, \nabla_{e_1}e_2 = 0, \nabla_{e_1}e_3 = e_1,$$

$$\nabla_{e_2}e_1 = 0, \nabla_{e_2}e_2 = e_3, \nabla_{e_2}e_3 = e_2,$$

$$\nabla_{e_3}e_1 = e_1, \nabla_{e_3}e_2 = e_2, \nabla_{e_3}e_3 = 0.$$

These results shows that the manifold satisfies

$$\nabla_X \xi = X - \eta(X)\xi,$$

for $\xi = e_3$. Hence the manifold under consideration is para-Kenmotsu manifold of dimension three.

A para-Kenmotsu manifold is said to be an η -Einstein manifold if its Ricci tensor S is of the form

$$S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y)$$
(17)

for the vector fields X, Y, where a and b are functions on M^n .

3 Generalized pseudo-projective curvature tensor of para-Kenmotsu manifold

In this section, we give a brief account of generalized pseudo-projective curvature tensor of para-Kenmotsu manifold and study various geometric properties of it.

The pseudo-projective curvature tensor of para-Kenmotsu manifold M^n is given by the following relation:

$$P(X, Y, U) = aR(X, Y, U) + b[S(Y, U)X - S(X, U)Y] - \frac{r}{n} \left(\frac{a}{n-1} + b\right) [g(Y, U)X - g(X, U)Y],$$
(18)

Also, the type (0,4) tensor field \overline{P} is given by

$$\overline{P}(X, Y, U, V) = a'R(X, Y, U, V) + b[S(Y, U)g(X, V) - S(X, U) g(Y, V)] - \frac{r}{n} \left(\frac{a}{n-1} + b\right) [g(Y, U)g(X, V) - g(X, U)g(Y, V)],$$
(19)

where

$$\overline{P}(X,Y,U,V) = g(\overline{P}(X,Y,U),V)$$

and

$$'R(X, Y, U, V) = g(R(X, Y, U), V)$$

for the arbitrary vector fields X, Y, U, V.

Differentiating covariantly with respect to W in equation (18), we get

$$(\nabla_W \overline{P})(X, Y)U) = a(\nabla_W R)(X, Y)U) + b[(\nabla_W S)(Y, U)X$$

$$-(\nabla_W S)(X, U)Y] - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right) [g(Y, U)X - g(X, U)Y].$$
 (20)

Divergence of pseudo-projective curvature tensor in equation (18) is given by

$$(div\overline{P})(X,Y)U) = a(divR)(X,Y)U) + b[(\nabla_X S)(Y,U) - (\nabla_Y S)(X,U)] - (divr) \left[\frac{a+b(n-1)}{n(n-1)}\right] [g(Y,U)div(X) -g(X,U)div(Y)].$$
(21)

But

$$(divR)(X,Y)U) = (\nabla_X S)(Y,U) - (\nabla_Y S)(X,U).$$
(22)

From equations (21) and (22), we have

$$(div\overline{P})(X,Y)U) = (a+b)[(\nabla_X S)(Y,U) - (\nabla_Y S)(X,U)] - (divr)$$
$$\left[\frac{a+b(n-1)}{n(n-1)}\right] [g(Y,U)div(X) - g(X,U)div(Y)].$$
(23)

Definition 2. An almost paracontact structure (ϕ, ξ, η, g) is said to be locally pseudo-projectively symmetric if

$$(\nabla_W \overline{P})(X, Y, U) = 0, \qquad (24)$$

for all vector fields $X, Y, U, W \in T_p M^n$.

Definition 3. An almost paracontact structure (ϕ, ξ, η, g) is said to be locally pseudo-projectively ϕ -symmetric if

$$\phi^2((\nabla_W \overline{P})(X, Y, U)) = 0, \qquad (25)$$

for all vector fields X, Y, U, W orthogonal to ξ .

Definition 4. An almost paracontact structure (ϕ, ξ, η, g) is said to be pseudoprojectively ϕ -recurrent if

$$\phi^2((\nabla_W \overline{P})(X, Y, U)) = A(W)\overline{P}(X, Y, U), \tag{26}$$

for arbitrary vector fields X, Y, U, W.

If the 1-form A vanishes, then the manifold reduces to a locally pseudoprojectively ϕ -symmetric.

A new generalized (0,2) symmetric tensor \mathbb{Z} , defined by Mantica and Suh [9], is given by the following relation

$$\mathcal{Z}(X,Y) = S(X,Y) + \psi g(X,Y), \qquad (27)$$

where ψ is an arbitrary scalar function. From equation (27), we have

$$\mathcal{Z}(\phi X, \phi Y) = S(\phi X, \phi Y) + \psi g(\phi X, \phi Y), \tag{28}$$

which, on using equations (7) and (13), gives

$$\mathcal{Z}(\phi X, \phi Y) = [\psi - (n-1)][-g(X,Y) + \eta(X)\eta(Y)].$$
(29)

From equation (19), we have

$${}^{\prime}\overline{P}(X,Y,U,V) = a'R(X,Y,U,V) + b[S(Y,U)g(X,V) - S(X,U) g(Y,V)] - \frac{r}{n} \left(\frac{a}{n-1} + b\right) [g(Y,U)g(X,V) - g(X,U)g(Y,V)].$$
(30)

From equation (27) the above equation reduces to

$${}^{\prime}\overline{P}(X,Y,U,V) = a'R(X,Y,U,V) + b[\mathcal{Z}(Y,U)g(X,V) - \mathcal{Z}(X,U) g(Y,V)] - \frac{r}{n} \left(\frac{a}{n-1} + b\right) [g(Y,U)g(X,V) - g(X,U)g(Y,V)] + b\psi[g(Y,V)g(X,U) - g(Y,U)g(X,V)],$$
(31)

If we put

$$\overline{P}(X,Y,U,V) = a'R(X,Y,U,V) + b[\mathcal{Z}(Y,U)g(X,V) - \mathcal{Z}(X,U)$$

$$g(Y,V)] - \frac{r}{n}\left(\frac{a}{n-1} + b\right)[g(Y,U)g(X,V) - g(X,U)g(Y,V)].$$
(32)

Then equation (31) reduces to

$$\overline{P}(X,Y,U,V) = \overline{P}(X,Y,U,V) - b\psi[g(Y,V)g(X,U) - g(X,V)g(Y,U)].$$
(33)

We call this new tensor $\overline{\overline{P}}$ given in equation (32) as generalized pseudo-projective curvature tensor of para-Kenmotsu manifold.

If $\psi=0$, then from equation (33), we have

$$\overline{P}(X,Y,U,V) = \overline{P}(X,Y,U,V).$$
(34)

If the scalar function ψ vanishes on para-Kenmotsu manifold, then the pseudoprojective curvature tensor and generalized pseudo-projective curvature tensor are identicle.

Theorem 1. Generalized pseudo-projective curvature tensor $\overline{\overline{P}}$ of para-Kenmotsu manifold is

- (a) skew symmetric in first two slots.
- (b) skew symmetric in last two slots.
- (c) symmetric in pair of slots.

Proof. (a) From equation (33), we have

$$\overline{P}(Y, X, U, V) = \overline{P}(Y, X, U, V) - b\psi[g(X, V)g(Y, U) -g(Y, V)g(X, U)].$$
(35)

Now adding equations (33) and (35) and using the following

$$\overline{P}(X, Y, U, V) + \overline{P}(Y, X, U, V) = 0,$$

we get

$${}^{\prime}\overline{\overline{P}}(X,Y,U,V)=-{}^{\prime}\overline{\overline{P}}(Y,X,U,V),$$

which shows that generalized pseudo-projective curvature tensor \overline{P} is skew symmetric in first two slots.

(b) Again from equation (33), we have

$$\overline{P}(X, Y, V, U) = \overline{P}(X, Y, V, U) - b\psi[g(X, V)g(Y, U) - g(Y, V)g(X, U)].$$
(36)

Now, adding (33) and (36) and using the following

$$\overline{P}(X,Y,U,V) + \overline{P}(X,Y,V,U) = 0,$$

we obtain

$${}^{\prime}\overline{\overline{P}}(X,Y,U,V)=-{}^{\prime}\overline{\overline{P}}(X,Y,V,U),$$

which shows that generalized pseudo-projective curvature tensor \overline{P} is skew symmetric in last two slots.

(c) From equation (33), interchanging pair of slots X by U and Y by V, we have

$$\overline{P}(U, V, X, Y) = \overline{P}(U, V, X, Y) - b\psi[g(V, Y)g(U, X) -g(U, Y)g(V, X)].$$

$$(37)$$

Now, using equations (33) and (37) and using the following

$$\overline{P}(X,Y,U,V) = \overline{P}(U,V,X,Y),$$

we get

$$'\overline{P}(X,Y,U,V) = '\overline{P}(U,V,X,Y),$$

which shows that generalized pseudo-projective curvature tensor \overline{P} is symmetric in pair of slots.

Theorem 2. Generalized pseudo-projective curvature tensor of para-Kenmotsu manifold satisfies Bianchi's first identity.

Proof. From equation (33), we have

$$\overline{P}(X,Y,U) = \overline{P}(X,Y,U) - b\psi[g(X,U)Y - g(Y,U)X)].$$
(38)

Writing two more equations by the cyclic permutations of X, Y and U in the above equation, we get

$$\overline{P}(Y,U,X) = \overline{P}(Y,U,X) - b\psi[g(Y,X)U - g(U,X)Y)]$$
(39)

and

$$\overline{P}(U,X,Y) = \overline{P}(U,X,Y) - b\psi[g(U,Y)X - g(X,Y)U)].$$
(40)

Adding equations (38), (39) and (40) with the fact that

$$\overline{P}(X,Y,U) + \overline{P}(Y,U,X) + \overline{P}(U,X,Y) = 0,$$

we get

$$\overline{\overline{P}}(X,Y,U) + \overline{\overline{P}}(Y,U,X) + \overline{\overline{P}}(U,X,Y) = 0,$$

which shows that generalized pseudo-projective curvature tensor of para-Kenmotsu manifold satisfies Bianchi's first identity. $\hfill \Box$

Theorem 3. Generalized pseudo-projective curvature tensor of para-Kenmotsu manifold satisfies the following identites:

$$(a)\overline{\overline{P}}(\xi, Y, U) = -\overline{\overline{P}}(Y, \xi, U) = g(Y, U) \left[-a - \frac{r}{n} \left(\frac{a}{n-1} + b \right) + b\psi \right]$$
$$\xi + \left[a + b(n-1) + \frac{r}{n} \left(\frac{a}{n-1} + b \right) - b\psi \right] \eta(U)Y$$
(41)

$$+bS(Y,U)\xi,$$

$$(b)\overline{\overline{P}}(X,Y,\xi) = \left[a+b(n-1)+\frac{r}{n}\left(\frac{a}{n-1}+b\right)-b\psi\right][\eta(X)Y -\eta(Y)X],$$
(42)

$$(c)\eta(\overline{\overline{P}}(U,V,Y)) = \left[a + \frac{r}{n}\left(\frac{a}{n-1} + b\right) - b\psi\right] [g(U,Y)\eta(V) -g(V,Y)\eta(U)] + b[S(V,Y)\eta(U) - S(U,Y)\eta(V)].$$

$$(43)$$

Proof. (a) Putting $X = \xi$ in equation (38), we have

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$$\overline{P}(\xi, Y, U) = \overline{P}(\xi, Y, U) - b\psi[g(\xi, U)Y - g(Y, U)\xi],$$

which on using equations (6), (12), (14), (18), gives the desired result.

(b) Again putting $U = \xi$ in equation (38), we have

$$\overline{P}(X,Y,\xi) = \overline{P}(X,Y,\xi) - b\psi[g(X,\xi)Y - g(Y,\xi)X].$$

With the use of equations (6), (11), (14), (18) in the above equation, we obtain the required result.

(c) Taking innner product with ξ of equation (38), we have

$$\eta(\overline{P}(U,V,Y)) = \eta(\overline{P}(U,V,Y)) - b\psi[g(U,Y)\eta(V) - g(V,Y)\eta(U)],$$

which on using equations (6), (10), (18), gives the desired result.

4 Generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold

Definition 5. A Para-Kenmotsu manifold is said to be semi-symmetric [23] if it satisfies the condition

$$R(X,Y) \cdot R = 0, \tag{44}$$

where R(X, Y) is considered as the derivation of the tensor algebra at each point of the manifold.

Definition 6. A para-Kenmotsu manifold is said to be generalized pseudoprojectively semi-symmetric if it satisfies the condition

$$R(X,Y) \cdot \overline{P} = 0, \tag{45}$$

where $\overline{\overline{P}}$ is generalized pseudo-projective curvature tensor and R(X,Y) is considered as the derivation of the tensor algebra at each point of the manifold.

Theorem 4. A generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold is an η -Einstein manifold.

Proof. Consider

$$(R(\xi, X) \cdot \overline{P})(U, V, Y) = 0,$$

for any $X, Y, U, V \in T_P M$, where $\overline{\overline{P}}$ is generalized Pseudo-projective curvature tensor.

Then we have

$$R(\xi, X, \overline{\overline{P}}(U, V, Y)) - \overline{\overline{P}}(R(\xi, X, U), V, Y) -\overline{\overline{P}}(U, R(\xi, X, V), Y) - \overline{\overline{P}}(U, V, R(\xi, X, Y) = 0.$$
(46)

In view of equation (12) the above equation takes the form

$$\begin{split} \eta(\overline{\overline{P}}(U,V,Y))X &-' \overline{\overline{P}}(U,V,Y,X)\xi - \eta(U)\overline{\overline{P}}(X,V,Y) + g(X,U)\\ \overline{\overline{P}}(\xi,V,Y) &- \eta(V)\overline{\overline{P}}(U,X,Y) + g(X,V)\overline{\overline{P}}(U,\xi,Y) - \eta(Y)\overline{\overline{P}}(U,V,X)\\ &+ g(X,Y)\overline{\overline{P}}(U,V,\xi) = 0. \end{split}$$

Taking inner product of above equation with ξ and using equations (5), (33), (41), (42), (43), we get

$$\begin{aligned} -'\overline{P}(U,V,Y,X) + b\psi[g(X,V)g(Y,U) - g(X,U)g(Y,V)] - bg(X,V) \\ S(Y,U) - \left[a + \frac{r}{n}\left(\frac{a}{n-1} + b\right) - b\psi\right] \left[g(X,U)\eta(Y)\eta(V) - g(X,V) \\ \eta(Y)\eta(U)\right] - \left[a + b(n-1) + \frac{r}{n}\left(\frac{a}{n-1} + b\right) - b\psi\right] g(X,V)\eta(Y)\eta(U) \\ + bg(X,U)S(Y,V) - b[S(X,V)\eta(U)\eta(Y) - S(X,U)\eta(V)\eta(Y)] \\ + g(X,U)\eta(Y)\eta(V) \left[a + b(n-1) + \frac{r}{n}\left(\frac{a}{n-1} + b\right) - b\psi\right] \\ - g(X,V)g(Y,U) \left[-a - \frac{r}{n}\left(\frac{a}{n-1} + b\right) + b\psi\right] + g(X,U)g(Y,V) \\ \left[-a - \frac{r}{n}\left(\frac{a}{n-1} + b\right) + b\psi\right] = 0. \end{aligned}$$

By virtue of equation (19), the above equation reduces to

$$\begin{aligned} -a'R(U,V,Y,X) &+ \frac{r}{n}\left(\frac{a}{n-1}+b\right)\left[g(Y,V)g(U,X) - g(Y,U)\right.\\ g(V,X)\right] &- \left[a + \frac{r}{n}\left(\frac{a}{n-1}+b\right) - b\psi\right]\left[g(U,X)\eta(Y)\eta(V)\right.\\ &- g(V,X)\eta(Y)\eta(U)\right] &+ \left[a + b(n-1) + \frac{r}{n}\left(\frac{a}{n-1}+b\right) - b\psi\right]\\ g(X,U)\eta(Y)\eta(V) &- \left[a + b(n-1) + \frac{r}{n}\left(\frac{a}{n-1}+b\right) - b\psi\right]\\ g(X,V)\eta(Y)\eta(U) &- g(X,V)g(Y,U)\left[-a - \frac{r}{n}\left(\frac{a}{n-1}+b\right) + b\psi\right]\\ &+ g(X,U)g(Y,V)\left[-a - \frac{r}{n}\left(\frac{a}{n-1}+b\right) + b\psi\right]\\ &- b[S(X,V)\eta(U)\eta(Y) - S(X,U)\eta(V)\eta(Y)]\\ &+ b\psi[g(Y,U)g(X,V) - g(Y,V)g(X,U)] = 0. \end{aligned}$$

Let $\{e_i : i = 1, 2, ..., n\}$ be an orthonormal basis. Putting $X = U = e_i$ in the above equation and taking summation over *i*, we get

$$S(Y,V) = -(n-1)g(Y,V) + \frac{2nb}{a}\eta(Y)\eta(V).$$

This shows that generalized pseudo-projectively semi-symmetric para-Kenmotsu manifold is an η -Einstein manifold.

5 Generalized pseudo-projectively Ricci semisymmetric para-Kenmotsu manifold

Definition 7. Para-Kenmotsu manifold M is said to be Ricci semi-symmetric [10] if the condition

$$R(X,Y) \cdot S = 0, \tag{47}$$

holds for all $X, Y \in T_p M$.

Definition 8. Para-Kenmotsu manifold is said to be generalized pseudo-projectively Ricci semi-symmetric if the condition

$$\overline{P}(X,Y) \cdot S = 0, \tag{48}$$

holds for all X, Y, where $\overline{\overline{P}}$ is generalized pseudo-projective curvature tensor of para-Kenmotsu manifold.

Theorem 5. A generalized pseudo-projectively Ricci semi-symmetric para-Kenmotsu manifold is either Einstein manifold or $\psi = \frac{an(n-1)+ra+br(n-1)}{bn(n-1)}$ on it.

Proof. Consider

$$(\overline{\overline{P}}(\xi, X) \cdot S)(U, V) = 0,$$

which gives

$$S(\overline{\overline{P}}(\xi, X, U), V) + S(U, \overline{\overline{P}}(\xi, X, V)) = 0.$$

Using equations (14) and (41) in the above equation, we get

$$0 = \left[a + \frac{r}{n}\left(\frac{a}{n-1} + b\right) - b\psi\right] \left[S(X,V)\eta(U) + S(X,U)\eta(V)\right]$$
$$- (n-1)\left[-a - \frac{r}{n}\left(\frac{a}{n-1} + b\right) + b\psi\right] \left[g(X,U)\eta(V) + g(X,V)\eta(U)\right]$$

Putting $U = \xi$ in the above equation and using (5), (6) and (14), we get

$$\left[a + \frac{r}{n}\left(\frac{a}{n-1} + b\right) - b\psi\right]\left[S(X,V) + (n-1)g(X,V)\right] = 0,$$

which gives either

$$\psi = \frac{an(n-1) + ra + br(n-1)}{bn(n-1)}$$

or

$$S(X,V) = -(n-1)g(X,V).$$

This shows that generalized pseudo-projectively Ricci semi-symmetric para-Kenmotsu manifold is an Einstein manifold. $\hfill \Box$

6 Generalized pseudo-projectively ϕ -symmetric para-Kenmotsu manifold

Definition 9. A para-Kenmotsu manifold M^n is said to be locally ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y, U)) = 0, \tag{49}$$

for all vector fields X, Y, U, W orthogonal to ξ .

This notion was introduced by Takahashi for Sasakian manifolds [24].

Definition 10. A para-Kenmotsu manifold is said to be ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y, U)) = 0, \tag{50}$$

for arbitrary vector fields X, Y, U, W.

This notion was also introduced by Takahashi for Sasakian manifold [25]. Also analogous to these definitons, we define

On generalized pseudo-projective curvature tensor ...

Definition 11. A para-Kenmotsu manifold M^n is said to be generalized pseudoprojective locally ϕ -symmetric para-Kenmotsu manifold if

$$\phi^2((\nabla_W \overline{\overline{P}})(X, Y, U)) = 0, \tag{51}$$

for all vector fields X, Y, U, W orthogonal to ξ .

And also

Definition 12. A para-Kenmotsu manifold M^n is said to be generalized pseudoprojectively ϕ -symmetric para-Kenmotsu manifold if

$$\phi^2((\nabla_W \overline{P})(X, Y, U)) = 0, \tag{52}$$

for arbitrary vector fields X, Y, U, W.

Theorem 6. A generalized pseudo projectively ϕ -symmetric para Kenmotsu manifold is an Einstein manifold.

Proof. Taking covariant derivative of equation (38) with respect to vector field W, we obtain

$$(\nabla_W \overline{\overline{P}})(X, Y, U) = (\nabla_W \overline{P})(X, Y, U) - bdr(\psi)[g(X, U)Y - g(Y, U)X].$$
(53)

Using equation (20) in the above equation, we get

$$(\nabla_W \overline{\overline{P}})(X, Y, U) = a(\nabla_W R)(X, Y, U) - bdr(\psi)[g(X, U)Y - g(Y, U)X] + b[(\nabla_W S)(Y, U)X - (\nabla_W S)(X, U)Y] - \frac{dr(W)}{n}$$

$$\left(\frac{a}{n-1} + b\right)[g(Y, U)X - g(X, U)Y],$$
(54)

Assume that the manifold is generalized pseudo-projectively ϕ -symmetric, then from equation (52), we have

$$\phi^2((\nabla_W \overline{\overline{P}})(X, Y, U)) = 0,$$

which on using equation (2), gives

$$(\nabla_W \overline{\overline{P}})(X, Y, U) = \eta((\nabla_W \overline{\overline{P}})(X, Y, U))\xi.$$
(55)

Using equation (54) in above equation, we get

$$a(\nabla_W R)(X, Y, U) - bdr(\psi)[g(X, U)Y - g(Y, U)X] + b$$

$$[(\nabla_W S)(Y, U)X - (\nabla_W S)(X, U)Y] - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right)$$

$$[g(Y, U)X - g(X, U)Y] = a\eta((\nabla_W R)(X, Y, U))\xi - bdr(\psi)$$

$$[g(X, U)\eta(Y) - g(Y, U)\eta(X)]\xi + b[(\nabla_W S)(Y, U)\eta(X)$$

$$-(\nabla_W S)(X, U)\eta(Y)]\xi - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right)$$

$$[g(Y, U)\eta(X) - g(X, U)\eta(Y)]\xi,$$
(56)

Taking inner product of the above equation with V, we get

$$ag((\nabla_{W}R)(X,Y,U),V) - bdr(\psi)[g(X,U)g(Y,V) - g(Y,U) g(X,V)] + b[(\nabla_{W}S)(Y,U)g(X,V) - (\nabla_{W}S)(X,U)g(Y,V)] - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right) [g(Y,U)g(X,V) - g(X,U)g(Y,V)] = a\eta((\nabla_{W}R)(X,Y,U))\eta(V) - bdr(\psi)[g(X,U)\eta(Y)\eta(V) - g(Y,U)\eta(X)\eta(V)] + b[(\nabla_{W}S)(Y,U)\eta(X)\eta(V) - (\nabla_{W}S)(X,U)\eta(Y)\eta(V)] - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right) [g(Y,U)\eta(X)\eta(V) - g(X,U)\eta(Y)\eta(V)].$$
(57)

Putting $X = V = e_i$ and taking summation over *i*, we obtain

$$a(\nabla_{W}S)(Y,U) + b[n(\nabla_{W}S)(Y,U) - (\nabla_{W}S)(Y,U)] - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right) [ng(Y,U) - g(Y,U)] - bdr(\psi)[g(Y,U) - ng(Y,U)] - a\eta((\nabla_{W}R)(e_{i},Y,U))\eta(e_{i})$$
(58)
$$-b[(\nabla_{W}S)(Y,U) - (\nabla_{W}S)(e_{i},U)\eta(Y)\eta(e_{i}) + \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right) [g(Y,U) - \eta(Y)\eta(U)] + bdr(\psi)[\eta(U)\eta(Y) - g(Y,U)] = 0,$$

Taking $U = \xi$ in the above equation, we have

$$a(\nabla_{W}S)(Y,\xi) + b(n-1)(\nabla_{W}S)(Y,\xi) - \frac{dr(W)}{n} \left(\frac{a}{n-1} + b\right) (n-1)\eta(Y) - a\eta((\nabla_{W}R)(e_{i},Y,\xi))\eta(e_{i}) + bdr(\psi)(n-1)\eta(Y) -b[(\nabla_{W}S)(Y,\xi) - (\nabla_{W}S)(e_{i},\xi)\eta(e_{i})\eta(Y)] = 0.$$
(59)

Now

$$\eta((\nabla_W R)(e_i, Y, \xi)\eta(e_i) = g((\nabla_W R)(e_i, Y, \xi), \xi)g(e_i, \xi).$$
(60)

Also

$$g((\nabla_W R)(e_i, Y, \xi), \xi) = g(\nabla_W R(e_i, Y, \xi), \xi) - g(R(\nabla_W e_i, Y, \xi), \xi) - g(R(e_i, \nabla_W Y, \xi), \xi) - g(R(e_i, Y, \nabla_W \xi), \xi).$$
(61)

Since $\{e_i\}$ is an orthonormal basis, so $\nabla_X e_i = 0$ and using equation (11), we get

$$g(R(e_i, \nabla_W Y, \xi), \xi) = 0.$$

Since

$$g(R(e_i, Y, \xi), \xi) + g(R(\xi, \xi, Y), e_i) = 0$$

Therefore, we have

$$g(\nabla_W R(e_i, Y, \xi), \xi) + g(R(e_i, Y, \xi), \nabla_W \xi) = 0,$$

Using this fact in equation (61), we get

$$g((\nabla_W R)(e_i, Y, \xi), \xi) = 0.$$
(62)

Using equation (62) in (59), we have

$$\left[\frac{dr(W)}{n}\left(\frac{a}{n-1}+b\right)(n-1)\eta(Y) - bdr(\psi)(n-1)\eta(Y)\right] \\ \left[\frac{1}{a+b(n-1)-b}\right] = (\nabla_W S)(Y,\xi),$$
(63)

Taking $Y = \xi$ in above equation and using equations (5) and (14), we get

$$dr(\psi) = \frac{dr(W)}{bn} \left(\frac{a}{n-1} + b\right),\tag{64}$$

which shows that r is constant. Now we have

$$(\nabla_W S)(Y,\xi) = \nabla_W S(Y,\xi) - S(\nabla_W Y,\xi) - S(Y,\nabla_W \xi),$$

Then by using (8), (9), (14) in the above equation, it follows that

$$(\nabla_W S)(Y,\xi) = -S(Y,W) - (n-1)g(Y,W).$$
(65)

Thus from equations (63), (64) and (65), we obtain

$$S(Y,W) = -(n-1)g(Y,W),$$
(66)

which shows that M^n is an Einstein manifold.

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